# Callie Yejin Kim

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#### RESEARCH INTERESTS

My research focuses on user-centered methods to enhance feedback mechanisms and improve the reliability of LLM-driven robot programming. I explore how to empower non-experts to effectively interact with intelligent systems, combining technical development and user studies at the intersection of HCI, AI, and robotics.

#### **EDUCATION**

PhD, Computer Science

August 2021 - Present

University of Wisconsin-Madison, 3.44/4.00 cumulative GPA

Madison, WI

Advisor: Dr. Bilge Mutlu

M.S, Computer Science

August 2019 - May 2021

University of Maryland, 3.92/4.00 cumulative GPA

College Park, MD

Advisor: Dr. Huaishu Peng

**B.S.** Computer Science and Engineering

March 2015 - February 2019

Ewha Womans University, 3.78/4.00 cumulative GPA

Seoul, South Korea

# RESEARCH EXPERIENCES

#### Graduate Research Assistant - People and Robots Laboratory

Madison, WI

Advisor: Dr. Bilge Mutlu

July 2023 - Present

Robo-critic: Robot Program Generation with Multi-critic Verification
Implemented an LLM modulo framework that enables users to provide feedback in LLM-driven robot programming using critics

## University of Maryland - Dept. of Computer Science

College Park, MD

Advisor: Dr. Huaishu Peng

July 2020 - May 2021

Enabling Virtual Reality Experience for Visually Impaired People using Custom VR Headset

Designed and developed hardware prototypes that offer around-head haptic feedback to support visually impaired people to understand a scene in VR.

# **PUBLICATIONS**

**Kim, C.\***, Lee, C.\*, & Mutlu, B. Understanding Large-Language Model (LLM)-powered Human-Robot Interaction, In ACM/IEEE *Human Robot Interaction (HRI 24)*. 24.7% Acceptance Rate

<sup>\*</sup> indicates equal contribution

**Kim, C.**, Shin, I., Jung, H. (2018) Implementation of Google Cardboard Based VR Simulator for Disaster Evacuation Training, In *Proceedings of Korea Multimedia Society* 

#### PRESENTATIONS

**Kim, C.**, Shin, I., Jung, H. (2018) Mobile VR Simulation for Disaster Evacuation Training, Poster session presented at *Hanium Expo, Goyang-si, South Korea* 

#### TEACHING EXPERIENCE

Teaching Assistant, University of Wisconsin-Madison

January 2022 - December 2024

CS400 Programming III

Teaching Assistant, University of Wisconsin-Madison

August 2021 - December 2021

CS537 Introduction to Operating Systems

Teaching Assistant, University of Maryland

August 2020 – May 2021

CMSC425 Game Programming

## AWARDS AND SCHOLARSHIPS

Honors Scholarship, Ewha Womans University

September 2018

Honors Scholarship, Ewha Womans University

September 2017

Grand prize, NEXON Dream Members, NEXON

March 2017

Dean's list, Ewha Womans University

March 2015 - June 2018

#### INVITED TALKS

October 12th, 2024, Large-Language Models (LLM) for Human-Robot Interaction. Mentorship Program on HRI and Robot Learning, *University of Virginia* 

# **PATENT**

Sangsoo Park, Callie Y. Kim, Ina Shin, and Hyunkyung Jung. Virtual Reality Based Disaster Education Method, Device and Computer Readable Medium for Performing the Method. KR Patent Application No. 1020180160585 filed Dec 13, 2018, Registration No. 1021139260000 registered May 15, 2020

# SERVICES

Grandparents University, Instructor, University of Wisconsin-Madison

Annually: July 2022, 2023, 2024

- · Led workshops teaching novel technologies, including robots and AI, to grandparents and grandchildren.
- Designed interactive activities to bridge generational gaps in technology understanding.

- Held seminars about game development in semesters and developed games in holidays. Organized game projects which were sponsored by NEXON and LINE Plus.